

March 23-24, 2018 Chicago, IL

# **Course Directors**

T. Sloane Guy, New York, NY Joseph A. Dearani, Rochester, MN Husam H. Balkhy, Chicago, IL

#### <u>Day 1</u>

Friday, March 23, 2018 (7:00 a.m. – 6:00 p.m.)

7:00 a.m. – 7:30 a.m.	REGISTRATION / BREAKFAST
7:30 a.m. – 9:00 a.m.	Session 1: Building a Foundation for Robotic Cardiac Surgery Moderators: Joseph A. Dearani, Rochester, MN, T. Sloane Guy, New York, NY, and Husam H. Balkhy, Chicago, IL
7:30 a.m. – 7:35 a.m.	Symposium Goals, Welcome, and Introductions
7:35 a.m. – 7:50 a.m.	Current Clinical and Economic Evidence for Robotic Cardiac Surgery A. Marc Gillinov, Cleveland OH
7:50 a.m. – 8:05 a.m.	Prerequisites for Successful Launch of a Robotic Cardiac Surgery Program Evelio Rodriguez, Nashville, TN
8:05 a.m. – 8:20 a.m.	What Does a Fully Committed Robotic Cardiac Surgery Program Look Like and What Procedures Can Be Performed? <i>Husam H. Balkhy, Chicago, IL</i>
8:20 a.m. – 8:35 a.m.	Detailed Steps for Building a Robotic Cardiac Surgery Program <i>T. Sloane Guy, New York, NY</i>
8:35 a.m. – 8:50 a.m.	Individual and Team Training in Robotic Surgery: What Are the options? Douglas A. Murphy, Atlanta, GA
8:50 a.m. – 9:00 a.m.	Panel Discussion
9:00 a.m. – 9:20 a.m.	BREAK
9:20 a.m. – 10:55 a.m.	Session 2: Robotic Mitral Valve Procedural Details Moderators: Evelio Rodriguez, Nashville, TN, and Vinay Badhwar, Morgantown, WV

9:20 a.m. – 9:35 a.m.	Patient Selection for Robotic Mitral Valve Surgery A. Marc Gillinov, Cleveland OH
9:35 a.m. – 9:50 a.m.	Circulatory Management Strategy: Transthoracic Clamp Technique Joseph A. Dearani, Rochester, MN
9:50 a.m. – 10:05 a.m.	Circulatory Management Strategy: Endoballoon Douglas A. Murphy, Atlanta, GA
10:05 a.m. – 10:20 a.m.	Totally Endoscopic Robotic Mitral Valve Repair: Step by Step <i>T. Sloane Guy, New York, NY</i>
10:20 a.m. – 10:35 a.m.	Minithoracotomy Robotic Mitral Valve Repair: Step by Step Simon Maltais, Rochester, MN
10:35 a.m. – 10:55 a.m.	Panel Discussion
10:55 a.m. – 11:15 a.m.	BREAK
11:15 a.m. – 12:55 p.m.	<ul> <li>Breakout Sessions: Procedure Demonstrations</li> <li>Station 1: Live Simulation/Demonstration Robotic Mitral Valve Repair Douglas A. Murphy, Atlanta, GA</li> <li>Station 2: Live Simulation/Demonstration Robotic Totally Endoscopic Coronary Artery Bypass (TECAB) Husam H. Balkhy, Chicago, IL</li> <li>Station 3: Live Simulation/Demonstration Robotic Minimally Invasive Direct Coronary Artery Bypass (MIDCAB) Francis P. Sutter, Wynnewood, PA</li> <li>Station 4: Hands-On Robotic Surgery Simulator Exercise Live Simulation/Demonstration: Advanced Circulatory Management T. Sloane Guy, New York, NY</li> </ul>
12:55 p.m. – 2:15 p.m.	LUNCH
2:15 p.m. – 3:50 p.m.	Session 3: Robotic Coronary Artery Bypass Basic Principles Moderators: Daniel M. Bethencourt, Long Beach, CA, and Francis P. Sutter, Wynnewood, PA
2:15 p.m. – 2:30 p.m.	Robotic Coronary Surgery: Anesthesia Considerations, Patient Positioning, and Port Placement <i>Richard C. Daly, Rochester, MN</i>

2:30 p.m. – 2:45 p.m.	Robotic MIDCAB: How I Do It and Lessons from a 15-Year Experience Daniel M. Bethencourt, Long Beach, CA
2:45 p.m. – 3:00 p.m.	Robotic MIDCAB: The 'Micro' Thoracotomy Approach Francis P. Sutter, Wynnewood, PA
3:00 p.m. – 3:15 p.m.	Robotic MIDCAB: Making the Transition from an Off-Pump Coronary Artery Bypass Mindset John D. Puskas, New York, NY
3:15 p.m. – 3:30 p.m.	Robotic MIDCAB: Postop Considerations, Fast Track, Pain Management Nirav C. Patel, New York, NY
3:30 p.m. – 3:50 p.m.	Panel Discussion
3:50 p.m. – 4:10 p.m.	BREAK
4:10 p.m. – 6:00 p.m.	Session 4: Mitral Valve Repair Techniques and Avoiding Complications Moderators: Douglas A. Murphy, Atlanta, GA, and T. Sloane Guy, New York, NY
4:10 p.m. – 4:25 p.m.	Robotic Mitral Valve Repair: Resectional Techniques Joseph A. Dearani, Rochester, MN
4:25 p.m. – 4:40 p.m.	Robotic Mitral Valve Repair: Non-Resectional Techniques <i>T. Sloane Guy, New York, NY</i>
4:40 p.m. – 4:55 p.m.	Robotic Mitral Valve Replacement Branden R. Reynolds, Spokane, WA
4:55 p.m. – 5:10 p.m.	Video Session: Complex Robotic Mitral Valve Repairs Vinay Badhwar, Morgantown, WV
5:10 p.m. – 5:25 p.m.	Avoiding Complications in Robotic Mitral Valve Repair A. Marc Gillinov, Cleveland OH
5:25 p.m. – 5:40 p.m.	When, Why, and How to Convert from Robotics to Open Surgery Simon Maltais, Rochester, MN
5:40 p.m. – 6:00 p.m.	Panel Discussion

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#### <u>Day 2</u> Saturday, March 24, 2018 (7:00 a.m. – 5:00 p.m.)

7:00 a.m. – 7:30 a.m.	REGISTRATION / BREAKFAST
7:30 a.m. – 9:05 a.m.	Session 5: TECAB Moderators: Husam H. Balkhy, Chicago, IL, and Johannes Bonatti, Abu Dhabi, United Arab Emirates
7:30 a.m. – 7:45 a.m.	The Case for TECAB: Value of Robotic TECAB versus Robotic MIDCAB Johannes Bonatti, Abu Dhabi, United Arab Emirates
7:45 a.m. – 8:00 a.m.	Robotic TECAB: Port Placement, Taking Down the RIMA Husam H. Balkhy, Chicago, IL
8:00 a.m. – 8:15 a.m.	Robotic Beating Heart TECAB: Stabilizer, Hand-Sewn Anastomosis Louis Labrousse, Bordeaux, France
8:15 a.m. – 8:30 a.m.	Robotic TECAB: The Arrested Heart Approach Johannes Bonatti, Abu Dhabi, United Arab Emirates
8:30 a.m. – 8:45 a.m.	Robotic TECAB: Using the Coronary Anastomotic Connector Husam H. Balkhy, Chicago, IL
8:45 a.m. – 9:05 a.m.	Panel Discussion
9:05 a.m. – 9:25 a.m.	BREAK
9:25 a.m. – 11:00 a.m.	Session 6: Robotic Intracardiac Surgery, More than Just the Mitral! Moderators: Douglas A. Murphy, Atlanta, GA, and A. Marc Gillinov, Cleveland OH
9:25 a.m. – 9:40 a.m.	Redo Robotic Mitral Valve Surgery Clifton T. Lewis, Birmingham, AL
9:40 a.m. – 9:55 a.m.	Atrial Fibrillation Techniques in Robotics Evelio Rodriguez, Nashville, TN
9:55 a.m. – 10:10 a.m.	Tricuspid Valve Repair and Replacement Clifton T. Lewis, Birmingham, AL
10:10 a.m. – 10:25 a.m.	Atrial Septal Defect Closure and Cardiac Tumor Resection Branden R. Reynolds, Spokane, WA

10:25 a.m. – 10:40 a.m.	Postoperative Management Joseph A. Dearani, Rochester, MN	
10:40 a.m. – 11:00 a.m.	Panel Discussion	
11:00 a.m. – 12:40 p.m.	Breakout Sessions: Procedure Demonstrations	
	Station 1: Live Simulation/Demonstration Robotic Mitral Valve Repair Douglas A. Murphy, Atlanta, GA	
	Station 2: Live Simulation/Demonstration Robotic TECAB Husam H. Balkhy, Chicago, IL	
	Station 3: Live Simulation/Demonstration Robotic MIDCAB	
	<ul> <li>Francis P. Sutter, Wynnewood, PA</li> <li>Station 4: Hands-On Robotic Surgery Simulator Exercise <ul> <li>Live Simulation/Demonstration: Advanced Circulatory</li> <li>Management</li> <li>T. Sloane Guy, New York, NY</li> </ul> </li> </ul>	
12:40 p.m. – 1:30 p.m.	LUNCH	
1:30 p.m. – 3:05 p.m.	Session 7: Robotic Coronary Artery Bypass: Avoiding Problems Moderators: Richard C. Daly, Rochester, MN, and Nirav C. Patel, New York,	NY
1:30 p.m. – 1:45 p.m.	Robotic Coronary Surgery: Avoiding Pitfalls during Port Placement/Minithoracotomy Francis P. Sutter, Wynnewood, PA	
1:45 p.m. – 2:00 p.m.	Robotic Coronary Surgery: Avoiding Internal Mammary Artery Injury and Finding the Correct Target Louis Labrousse, Bordeaux, France	
2:00 p.m. – 2:15 p.m.	Robotic Coronary Surgery: Intraoperative Graft Patency Assessment: Is Routine Angiography Necessary? Daniel M. Bethencourt, Long Beach, CA	
2:15 p.m. – 2:30 p.m.	Robotic Coronary Surgery: When and How to Convert to Open Surgery Nirav C. Patel, New York, NY	

4:45 p.m. – 5:00 p.m.	FINAL COMMENTS AND ADJOURNMENT
4:25 p.m. – 4:45 p.m.	Panel Discussion
4:10 p.m. – 4:25 p.m.	Elements of a Successful Hybrid Program and the NIH Trial John D. Puskas, New York, NY
3:55 p.m. – 4:10 p.m.	Examples of Hybrid Cases: Advanced (Complex) Hybrids Francis P. Sutter, Wynnewood, PA
3:40 p.m. – 3:55 p.m.	The Case for Hybrid Coronary Revascularization Nirav C. Patel, New York, NY
3:25 p.m. – 3:40 p.m.	Advanced Techniques: Y Grafts, Sequentials, Multivessel TECAB Johannes Bonatti, Abu Dhabi, United Arab Emirates
3:25 p.m. – 4:45 p.m.	Session 8: Advanced Robotic Coronary Artery Bypass Concepts Moderators: John D. Puskas, New York, NY, and Husam H. Balkhy, Chicago, IL
3:05 p.m. – 3:25 p.m.	BREAK
2:45 p.m. – 3:05 p.m.	Panel Discussion
	Coronary Surgery: Avoiding Postoperative Complications (Bleeding, Pericarditis) Richard C. Daly, Rochester, MN
2:30 p.m2:45 p.m.	Robotic Beating Heart TECAB: Stabilizer, Hand-Sewn Anastomosis Robotic